MOHAMED SATHAK A J COLLEGE OF ENGINEERING

Sponsored by Mohamed Sathak Trust

(Approved by AICTE, New Delhi and Affiliated to Anna University, Chennai)

Siruseri IT Park, Egattur, Chennai 603 103

B.E-ELECTRICAL AND ELECTRONICS ENGINEERING

S.No	Name of the course that include experimental learning through Project Work/Internship/Mini Project 2020-2021
1	RO8591- Principles of Robotics
2	EE8009 -Control of Electrical Drives
3	IC8651 -Advanced Control System
4	EE8018 -Microcontroller Based System Design
5	EE8005 -Special Electrical Machines
6	EE8012 -Soft Computing Techniques
7	EE8601 -Solid State Drives
8	EE8003 -Power Systems Stability
9	EE8552 -Power Electronics
10	EE8501 -Power System Analysis
11	EE8403 -Measurement & Instrumentation
12	EE8016-Energy Management and Auditing
13	EE8251-Circuit Theory
14	EE8591-Digital Signal Processing
15	EC 8395-Communication Engineering

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RO8591 **PRINCIPLES OF ROBOTICS** L T P C
3 0 0 3

OBJECTIVES:

- To introduce the functional elements of Robotics
- To impart knowledge on the direct and inverse kinematics
- To introduce the manipulator differential motion and control
- To educate on various path planning techniques
- To introduce the dynamics and control of manipulators

UNIT I BASIC CONCEPTS 9

Brief history-Types of Robot–Technology-Robot classifications and specifications-Design and controlissues- Various manipulators – Sensors - work cell - Programming languages.

UNIT II DIRECT AND INVERSE KINEMATICS 9

Mathematical representation of Robots - Position and orientation – Homogeneous transformation-Various joints- Representation using the Denavit Hattenberg parameters -Degrees of freedom-Direct kinematics-Inverse kinematics- SCARA robots- Solvability – Solution methods-Closed form solution.

UNIT III MANIPULATOR DIFFERENTIAL MOTION AND STATICS 9

Linear and angular velocities-Manipulator Jacobian-Prismatic and rotary joints–Inverse -Wrist and arm singularity - Static analysis - Force and moment Balance.

UNIT IV PATH PLANNING 9

Definition-Joint space technique-Use of p-degree polynomial-Cubic polynomial-Cartesian space technique - Parametric descriptions - Straight line and circular paths - Position and orientation planning.

UNIT V DYNAMICS AND CONTROL 9

Lagrangian mechanics-2DOF Manipulator-Lagrange Euler formulation-Dynamic model –Manipulator control problem-Linear control schemes-PID control scheme-Force control of robotic manipulator.

TOTAL: 45 PERIODS

OUTCOMES:

- Ability to understand basic concept of robotics.
- To analyze Instrumentation systems and their applications to various
- To know about the differential motion add statics in robotics
- To know about the various path planning techniques.
- To know about the dynamics and control in robotics industries.

TEXT BOOKS:

1. R.K.Mittal and I.J.Nagrath, Robotics and Control, Tata McGraw Hill, New Delhi,4th Reprint, 2005.
2. JohnJ.Craig ,Introduction to Robotics Mechanics and Control, Third edition, Pearson Education, 2009.
3. M.P.Groover, M.Weiss, R.N. Nageland N. G.Odrej, Industrial Robotics, McGraw-Hill Singapore, 1996.

REFERENCES:

1. Ashitava Ghoshal, Robotics-Fundamental Concepts and Analysis', Oxford University Press, Sixth impression, 2010.
2. K. K.Appu Kuttan, Robotics, I K International, 2007.
3. Edwin Wise, Applied Robotics, Cengage Learning, 2003.
4. R.D.Klafter,T.A.Chimielewski and M.Negin, Robotic Engineering–An Integrated Approach, Prentice Hall of India, New Delhi, 1994.
5. B.K.Ghosh, Control in Robotics and Automation: Sensor Based Integration, Allied Publishers,Chennai, 1998.
6. S.Ghoshal, " Embedded Systems & Robotics" – Projects using the 8051 Microcontroller", Cengage Learning, 2009.

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EE8009	CONTROL OF ELECTRICAL DRIVES	L	T	P	C
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OBJECTIVES: To impart knowledge about the following topics:

- To understand the DC drive control.
- To study and analyze the Induction motor drive control.
- To study and understand the Synchronous motor drive control.
- To study and analyze the SRM and BLDC motor drive control.
- To analyze and design the Digital control for drives.

UNIT I CONTROL OF DC DRIVES 9

Losses in electrical drive system, Energy efficient operation of drives, block diagram/ transfer function of self, separately excited DC motors –closed loop control-speed control-current control - constant torque/power operation - P, PI and PID controllers–response comparison.

UNIT II CONTROL OF INDUCTION MOTORDRIVE 9

VSI and CSI fed induction motor drives-principles of V/f control-closed loop variable frequency PWM inverter with dynamic braking- static Scherbius drives- power factor considerations– modified Kramer drives-principle of vector control- implementation-block diagram, Design of closed loop operation of V/f control of Induction motor drive systems.

UNIT III CONTROL OF SYNCHRONOUS MOTOR DRIVES 9

Open loop VSI fed drive and its characteristics–Self control–Torque control –Torque angle control –Power factor control–Brushless excitation systems—Field oriented control – Design of closed loop operation of Self control of Synchronous motor drive systems.

UNIT IV CONTROL OF SRM AND BLDC MOTOR DRIVES 9

SRM construction - Principle of operation - SRM drive design factors-Torque controlled SRM- Block diagram of Instantaneous Torque control using current controllers and flux controllers. Construction and Principle of operation of BLDC Machine -Sensing and logic switching scheme,-Sinusoidal and trapezoidal type of Brushless dc motors – Block diagram of current controlled Brushless dc motor drive.

UNIT V DIGITAL CONTROL OF DC DRIVE 9

Phase Locked Loop and micro-computer control of DC drives–Program flow chart for constant constant torque and constant horse power operations Speed detection and current sensing circuits and feedback elements.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to understand various control strategies and controllers for AC and DC Motor Drive systems.

TEXT BOOKS:

1. Dubey, G.K, Power semiconductor controlled devices, Prentice Hall International New jersey, 1989.
2. R.Krishnan,, Electric Motor Drives - Modeling, Analysis and ControlPrentice- Hall of India Pvt. Ltd., New Delhi, 2003.
3. Murphy, J.M.D, Turnbull F.G, Thyristor control of AC motors,., Pergamon press, Oxford, 1988.

REFERENCES

1. Bin Wu, High-Power Converters and AC Drives, Wiley-IEEE Press
2. Buxbaum, A.Schierau, and K.Staughen, A design of control systems for DC drives, Springer-Verlag, Berlin, 1990.
3. Bimal K. Bose, Modern Power Electronics and AC Drives, Pearson Education (Singapore) Pte. Ltd., New Delhi, 2003.
4. R. Krishnan, Switched Reluctance Motor Drives: Modeling, Simulation, Analysis, Design, and Applications, CRC press, 2001.
5. Werner Leonhard, Control of Electrical Drives, 3rd Edition, Springer, Sept., 2001.
6. R. Krishnan, Permanent Magnet Synchronous and Brushless DC Motor Drives, CRC press, 2001.

IC8651	ADVANCED CONTROL SYSTEM	LT P C 2 2 0 3

OBJECTIVES:

i. To provide knowledge on design state feedback control and state observer.
ii. To provide knowledge in phase plane analysis.
iii. To give basic knowledge in describing function analysis.
iv. To study the design of optimal controller.
v. To study the design of optimal estimator including Kalman Filter

UNIT I STATE VARIABLE ANALYSIS **6+6**

Introduction- concepts of state variables and state model-State model for linear continuous time systems, Diagonalisation- solution of state equations- Concepts of controllability and observability.

UNIT II STATE VARIABLE DESIGN **6+6**

Introduction to state model: Effect of state feedback - Pole placement design: Necessary and sufficient condition for arbitrary pole placement, State regulator design Design of state observers- Separation principle- Design of servo systems: State feedback with integral control.

UNIT III SAMPLED DATA ANALYSIS **6+6**

Introduction spectrum analysis of sampling process signal reconstruction difference equations The Z transform function, the inverse Z transform function, response of Linear discrete system, the Z transform analysis of sampled data control systems, response between sampling instants, the Z and S domain relationship. Stability analysis and compensation techniques.

UNIT IV NON LINEAR SYSTEMS **6+6**

Introduction, common physical nonlinearites, The phase plane method: concepts, singular points, stability of non linear systems, construction of phase trajectories system analysis by phase plane method. The describing function method, stability analysis by describing function method, Jump resonance.

UNIT V OPTIMAL CONTROL **6+6**

Introduction: Classical control and optimization, formulation of optimal control problem, Typical optimal control performance measures - Optimal state regulator design: Lyapunov equation, Matrix Riccati equation - LQR steady state optimal control – Application examples.

TOTAL: 60 PERIODS

OUTCOMES:

i. Able to design state feedback controller and state observer.
ii. Able to understand and analyse linear and nonlinear systems using phase plane method.
iii. Able to understand and analyse nonlinear systems using describing function method.
iv. Able to understand and design optimal controller.
v. Able to understand optimal estimator including Kalman Filter.
vi. Ability to apply advanced control strategies to practical engineering problems.

TEXT BOOKS:

1. M.Gopal, "Digital Control and State Variable Methods", 4th edition, Mc Graw Hill India, 2012
2. K. Ogata, 'Modern Control Engineering', 5th Edition, Pearson, 2012.
3. K. P. Mohandas, "Modern Control Engineering", Sanguine Technical Publishers, 2006.

REFERENCES:

1. M.Gopal, Modern Control System Theory, 3rd edition, New Age International Publishers, 2014.
2. William S Levine, "Control System Fundamentals," The Control Handbook, CRC Press, Tayler and Francies Group, 2011.
3. Ashish Tewari, 'Modern Control Design with Matlab and Simulink', John Wiley, New Delhi, 2002.
4. T. Glad and L. Ljung,, "Control Theory –Multivariable and Non-Linear Methods", Taylor & Francis, 2002.
5. D.S.Naidu, "Optimal Control Systems" First Indian Reprint, CRC Press, 2009.

EE8018	MICROCONTROLLER BASED SYSTEM DESIGN	L	T	P	C
		3	0	0	3

OBJECTIVES: To impart knowledge about the following topics:

- Architecture of PIC microcontroller
- Interrupts and timers
- Peripheral devices for data communication and transfer
- Functional blocks of ARM processor
- Architecture of ARM processors

UNIT I INTRODUCTION TO PIC MICROCONTROLLER **9**

Introduction to PIC Microcontroller–PIC 16C6x and PIC16C7x Architecture–IC16cxx–-Pipelining - Program Memory considerations – Register File Structure - Instruction Set - Addressing modes – Simple Operations.

UNIT II INTERRUPTS AND TIMER **9**

PIC micro controller Interrupts- External Interrupts-Interrupt Programming–Loop time subroutine Timers-Timer Programming– Front panel I/O-Soft Keys– State machines and key switches– Display of Constant and Variability strings.

UNIT III PERIPHERALS AND INTERFACING **9**

I^2C Bus for Peripherals Chip Access– Bus operation-Bus subroutines– Serial EEPROM—Analog to Digital Converter–UART-Baud rate selection–Data handling circuit–Initialization - LCD and keyboard Interfacing -ADC, DAC, and Sensor Interfacing.

UNIT IV INTRODUCTION TO ARM PROCESSOR **9**

Architecture –ARM programmer's model –ARM Development tools- Memory Hierarchy – ARM Assembly Language Programming–Simple Examples–Architectural Support for Operating systems.

UNIT V ARM ORGANIZATION **9**

3-Stage Pipeline ARM Organization– 5-Stage Pipeline ARM Organization–ARM Instruction Execution- ARM Implementation– ARM Instruction Set– ARM coprocessor interface–Architectural support for High Level Languages – Embedded ARM Applications.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to understand and apply computing platform and software for engineering problems.
- Ability to understand the concepts of Architecture of PIC microcontroller
- Ability to acquire knowledge on Interrupts and timers.
- Ability to understand the importance of Peripheral devices for data communication.
- Ability to understand the basics of sensor interfacing
- Ability to acquire knowledge in Architecture of ARM processors

TEXT BOOKS:

1. Peatman,J.B., "Design with PIC Micro Controllers"PearsonEducation,3rdEdition, 2004.
2. Furber,S., "ARM System on Chip Architecture" Addison Wesley trade Computer Publication, 2000.

REFERENCES

1. Mazidi, M.A.,"PIC Microcontroller" Rollin Mckinlay, Danny causey ,Prentice Hall of India, 2007.

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EE8005	SPECIAL ELECTRICAL MACHINES	L	T	P	C
		3	0	0	3

OBJECTIVES:

To impart knowledge on the following Topics

- Construction, principle of operation, control and performance of stepping motors.
- Construction, principle of operation, control and performance of switched reluctance motors.
- Construction, principle of operation, control and performance of permanent magnet brushless D.C. motors.
- Construction, principle of operation and performance of permanent magnet synchronous motors.
- Construction, principle of operation and performance of other special Machines.

UNIT I STEPPER MOTORS **9**

Constructional features –Principle of operation –Types – Torque predictions – Linear Analysis – Characteristics – Drive circuits – Closed loop control – Concept of lead angle - Applications.

UNIT II SWITCHED RELUCTANCE MOTORS (SRM) **9**

Constructional features –Principle of operation- Torque prediction–Characteristics Steady state performance prediction – Analytical Method – Power controllers – Control of SRM drive- Sensor less operation of SRM – Applications.

UNIT III PERMANENT MAGNET BRUSHLESS D.C. MOTORS **9**

Fundamentals of Permanent Magnets- Types- Principle of operation- Magnetic circuit analysis- EMF and Torque equations- Power Converter Circuits and their controllers - Characteristics and control- Applications.

UNIT IV PERMANENT MAGNET SYNCHRONOUS MOTORS (PMSM) **9**

Constructional features -Principle of operation – EMF and Torque equations - Sine wave motor with practical windings - Phasor diagram - Power controllers – performance characteristics -Digital controllers – Applications.

UNIT V OTHER SPECIAL MACHINES **9**

Constructional features – Principle of operation and Characteristics of Hysteresis motor- Synchronous Reluctance Motor–Linear Induction motor-Repulsion motor- Applications.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to analyze and design controllers for special Electrical Machines.
- Ability to acquire the knowledge on construction and operation of stepper motor.
- Ability to acquire the knowledge on construction and operation of stepper switched reluctance motors.
- Ability to construction, principle of operation, switched reluctance motors.
- Ability to acquire the knowledge on construction and operation of permanent magnet brushless D.C. motors.
- Ability to acquire the knowledge on construction and operation of permanent magnet synchronous motors.
- Ability to select a special Machine for a particular application.

TEXT BOOKS:

- K.Venkataratnam, 'Special Electrical Machines', Universities Press (India) Private Limited, 2008.
- T. Kenjo, 'Stepping Motors and Their Microprocessor Controls', Clarendon Press London, 1984
- E.G. Janardanan, 'Special electrical machines', PHI learning Private Limited, Delhi, 2014.

REFERENCES

1. R.Krishnan, 'Switched Reluctance Motor Drives – Modeling, Simulation, Analysis, Design and Application', CRC Press, New York, 2001.
2. T. Kenjo and S. Nagamori, 'Permanent Magnet and Brushless DC Motors', Clarendon Press, London, 1986.
3. T.J.E.Miller,'Brushless Permanent-Magnet and Reluctance Motor Drives', Oxford University Press, 1989.
4. R.Srinivasan, 'Special Electrical Machines', Lakshmi Publications, 2013.

EE8012 **SOFT COMPUTING TECHNIQUES** **L T P C**
3 0 0 3

OBJECTIVES: To impart knowledge about the following topics:

- Basics of artificial neural network.
- Concepts of modelling and control of neural and fuzzy control schemes.
- Features of hybrid control schemes.

UNIT I ARTIFICIAL NEURAL NETWORK **9**

Review of fundamentals – Biological neuron, artificial neuron, activation function, single layer perceptron – Limitation – Multi layer perceptron – Back Propagation Algorithm (BPA) – Recurrent Neural Network (RNN) – Adaptive Resonance Theory (ART) based network – Radial basis function network – online learning algorithms, BP through time – RTRL algorithms – Reinforcement learning.

UNIT II NEURAL NETWORKS FOR MODELING AND CONTROL **9**

Modelling of non-linear systems using ANN – Generation of training data – Optimal architecture– Model validation – Control of non-linear systems using ANN – Direct and indirect neuro control schemes – Adaptive neuro controller – Familiarization with neural network toolbox.

UNIT III FUZZY SET THEORY **9**

Fuzzy set theory – Fuzzy sets – Operation on fuzzy sets – Scalar cardinality, fuzzy cardinality, union and intersection, complement (Yager and Sugeno), equilibrium points, aggregation, projection, composition, cylindrical extension, fuzzy relation – Fuzzy membership functions.

UNIT IV FUZZY LOGIC FOR MODELING AND CONTROL **9**

Modelling of non-linear systems using fuzzy models – TSK model – Fuzzy logic controller – Fuzzification – Knowledge base – Decision making logic – Defuzzification – Adaptive fuzzy systems – Familiarization with fuzzy logic toolbox.

UNIT V HYBRID CONTROL SCHEMES **9**

Fuzzification and rule base using ANN – Neuro fuzzy systems – ANFIS – Fuzzy neuron–GA – Optimization of membership function and rule base using Genetic Algorithm – Introduction to other evolutionary optimization techniques, support vector machine– Case study – Familiarization with ANFIS toolbox.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to understand the concepts of ANN, different features of fuzzy logic and their modelling, control aspects and different hybrid control schemes.
- Ability to understand the basics of artificial neural network.
- Ability to get knowledge on modelling and control of neural.
- Ability to get knowledge on modelling and control of fuzzy control schemes.
- Ability to acquire knowledge on hybrid control schemes.
- Ability to understand the concepts of Adaptive Resonance Theory

TEXT BOOKS:

1. Laurence Fausett, "Fundamentals of Neural Networks", Prentice Hall, Englewood Cliffs, N.J., 1992
2. Timothy J. Ross, "Fuzzy Logic with Engineering Applications", McGraw Hill Inc., 2000.

REFERENCES

1. Goldberg, "Genetic Algorithm in Search, Optimization and Machine learning", Addison Wesley Publishing Company Inc. 1989
2. Miller W.T., Sutton R.S. and Webrose P.J., "Neural Networks for Control", MIT press, 1992
3. Ethem Alpaydin, "Introduction to Machine Learning (Adaptive Computation and Machine Learning series)', MIT Press, Second Edition, 2010
4. Zhang Huaguang and Liu Derong, "Fuzzy Modeling and Fuzzy Control Series: Control Engineering", 2006

EE8601 **SOLID STATE DRIVES** **L T P C**
3 0 0 3

OBJECTIVES:

To impart knowledge on the following Topics

- Steady state operation and transient dynamics of a motor load system.
- Analyze the operation of the converter/chopper fed dc drive, both qualitatively and quantitatively.
- Operation and performance of AC motor drives.
- Analyze and design the current and speed controllers for a closed loop solid state DC motor drive.

UNIT I DRIVE CHARACTERISTICS **9**

Electric drive – Equations governing motor load dynamics – steady state stability – multi quadrant Dynamics: acceleration, deceleration, starting & stopping – typical load torque characteristics – Selection of motor.

UNIT II CONVERTER / CHOPPER FED DC MOTOR DRIVE **9**

Steady state analysis of the single and three phase converter fed separately excited DC motor drive– continuous conduction – Time ratio and current limit control – 4 quadrant operation of converter / chopper fed drive-Applications.

UNIT III INDUCTION MOTOR DRIVES **9**

Stator voltage control–V/f control– Rotor Resistance control-qualitative treatment of slip power recovery drives-closed loop control— vector control- Applications.

UNIT IV SYNCHRONOUS MOTOR DRIVES **9**

V/f control and self-control of synchronous motor: Margin angle control and power factor control-Three phase voltage/current source fed synchronous motor- Applications.

UNIT V DESIGN OF CONTROLLERS FOR DRIVES **9**

Transfer function for DC motor / load and converter – closed loop control with Current and speed feedback–armature voltage control and field weakening mode – Design of controllers; current controller and speed controller- converter selection and characteristics.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to understand and suggest a converter for solid state drive.
- Ability to select suitability drive for the given application.
- Ability to study about the steady state operation and transient dynamics of a motor load system.
- Ability to analyze the operation of the converter/chopper fed dc drive.
- Ability to analyze the operation and performance of AC motor drives.
- Ability to analyze and design the current and speed controllers for a closed loop solid state DC motor drive.

TEXT BOOKS:

1. Gopal K.Dubey, Fundamentals of Electrical Drives, Narosa Publishing House, 1992.
2. Bimal K.Bose. Modern Power Electronics and AC Drives, Pearson Education, 2002.
3. R.Krishnan, Electric Motor & Drives: Modeling, Analysis and Control, Pearson, 2001.

REFERENCES

1. Vedam Subramanyam, " Electric Drives Concepts and Applications ", 2e, McGraw Hill, 2016
2. Shaahin Felizadeh, "Electric Machines and Drives", CRC Press (Taylor and Francis Group), 2013.
3. John Hindmarsh and Alasdain Renfrew, "Electrical Machines and Drives System," Elsevier 2012.
4. Theodore Wildi, " Electrical Machines ,Drives and power systems ,6th edition, Pearson Education ,2015.
5. N.K. De., P.K.SEN" Electric drives" PHI, 2012.

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EE8003 **POWER SYSTEM STABILITY** **L T P C**
3 0 0 3

OBJECTIVES:

- To understand the fundamental concepts of stability of power systems and its classification.
- To expose the students to dynamic behaviour of the power system for small and large disturbances.
- To understand and enhance the stability of power systems.

UNIT I INTRODUCTION TO STABILITY **9**

Fundamental concepts - Stability and energy of a system - Power System Stability: Definition, Causes, Nature and Effects of disturbances, Classification of stability, Modelling of electrical components - Basic assumptions made in stability studies- Modelling of Synchronous machine for stability studies(classical model) - Rotor dynamics and the swing equation.

UNIT II SMALL-SIGNAL STABILITY **9**

Basic concepts and definitions – State space representation, Physical Interpretation of small–signal stability, Eigen properties of the state matrix: Eigenvalues and eigenvectors, modal matrices, eigenvalue and stability, mode shape and participation factor. Small–signal stability analysis of a Single-Machine Infinite Bus (SMIB) Configuration with numerical example.

UNIT III TRANSIENT STABILITY **9**

Review of numerical integration methods: modified Euler and Fourth Order Runge-Kutta methods, Numerical stability,. Interfacing of Synchronous machine (classical machine) model to the transient stability algorithm (TSA) with partitioned – explicit approaches- Application of TSA to SMIB system.

UNIT IV VOLTAGE STABILITY **9**

Factors affecting voltage stability- Classification of Voltage stability-Transmission system characteristics- Generator characteristics- Load characteristics- Characteristics of reactive power compensating Devices- Voltage collapse.

UNIT V ENHANCEMENT OF SMALL-SIGNAL STABILITY AND TRANSIENT STABILITY **9**

Power System Stabilizer –. Principle behind transient stability enhancement methods: high-speed fault clearing, regulated shunt compensation, dynamic braking, reactor switching, independent pole-operation of circuit-breakers, single-pole switching, fast-valving, high-speed excitation systems.

TOTAL : 45 PERIODS

OUTCOMES:

- Learners will attain knowledge about the stability of power system
- Learners will have knowledge on small-signal stability, transient stability and voltage stability.
- Learners will be able to understand the dynamic behaviour of synchronous generator for different disturbances.
- Learners will be able to understand the various methods to enhance the stability of a power system.

TEXT BOOKS:

1. Power system stability and control ,P. Kundur ; edited by Neal J. Balu, Mark G. Lauby, McGraw-Hill, 1994.
2. R.Ramnujam," Power System Dynamics Analysis and Simulation, PHI Learning Private Limited, New Delhi, 2009
3. T.V. Cutsem and C.Vournas, "Voltage Stability of Electric Power Systems", Kluwer publishers, 1998.

REFERENCES

1. Peter W., Saucer, Pai M.A., "Power System Dynamics and Stability, Pearson Education (Singapore), 9th Edition, 2007.
2. EW. Kimbark., "Power System Stability", John Wiley & Sons Limited, New Jersey, 2013.
3. SB. Crary., "Power System Stability", John Wiley & Sons Limited, New Jersey, 1955.
4. K.N. Shubhanga,"Power System Analysis" Pearson, 2017.
5. Power systems dynamics: Stability and control / K.R. Padiyar, BS Publications, 2008
6. Power system control and Stability P.M. Anderson, A.A. Foud, Iowa State University Press, 1977.

EE8552 **POWER ELECTRONICS** **L T P C**
3 0 0 3

OBJECTIVES:

To impart knowledge on the following Topics

- Different types of power semiconductor devices and their switching
- Operation, characteristics and performance parameters of controlled rectifiers
- Operation, switching techniques and basics topologies of DC-DC switching regulators.
- Different modulation techniques of pulse width modulated inverters and to understand harmonic reduction methods.
- Operation of AC voltage controller and various configurations.

UNIT I POWER SEMI-CONDUCTOR DEVICES **9**

Study of switching devices, SCR, TRIAC, GTO, BJT, MOSFET, IGBT and IGCT- Static characteristics: SCR, MOSFET and IGBT - Triggering and commutation circuit for SCR- Introduction to Driver and snubber circuits.

UNIT II PHASE-CONTROLLED CONVERTERS **9**

2-pulse, 3-pulse and 6-pulseconverters– performance parameters –Effect of source inductance— Firing Schemes for converter–Dual converters, Applications-light dimmer, Excitation system, Solar PV systems.

UNIT III DC TO DC CONVERTERS **9**

Step-down and step-up chopper-control strategy– Introduction to types of choppers-A, B, C, D and E -Switched mode regulators- Buck, Boost, Buck- Boost regulator, Introduction to Resonant Converters, Applications-Battery operated vehicles.

UNIT IV INVERTERS **9**

Single phase and three phase voltage source inverters (both 120^0 mode and 180^0 mode)– Voltage& harmonic control--PWM techniques: Multiple PWM, Sinusoidal PWM, modified sinusoidal PWM – Introduction to space vector modulation –Current source inverter, Applications-Induction heating, UPS.

UNIT V AC TO AC CONVERTERS **9**

Single phase and Three phase AC voltage controllers–Control strategy- Power Factor Control – Multistage sequence control -single phase and three phase cyclo converters – Introduction to Matrix converters, Applications –welding .

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to analyse AC-AC and DC-DC and DC-AC converters.
- Ability to choose the converters for real time applications.

TEXT BOOKS:

1. M.H. Rashid, 'Power Electronics: Circuits, Devices and Applications', Pearson Education, Third Edition, New Delhi, 2004.
2. P.S.Bimbra "Power Electronics" Khanna Publishers, third Edition, 2003.
3. Ashfaq Ahmed 'Power Electronics for Technology', Pearson Education, Indian reprint, 2003.

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1. Joseph Vithayathil,' Power Electronics, Principles and Applications', McGraw Hill Series, 6th Reprint, 2013.
2. Philip T. Krein, "Elements of Power Electronics" Oxford University Press, 2004 Edition.
3. L. Umanand, "Power Electronics Essentials and Applications", Wiley, 2010.
4. Ned Mohan Tore. M. Undel and, William. P. Robbins, 'Power Electronics: Converters, Applications and Design', John Wiley and sons, third edition, 2003.
5. S.Rama Reddy, 'Fundamentals of Power Electronics', Narosa Publications, 2014.
6. M.D. Singh and K.B. Khanchandani, "Power Electronics," Mc Graw Hill India, 2013.
7. JP Agarwal," Power Electronic Systems: Theory and Design" 1e, Pearson Education, 2002.

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EE8501 **POWER SYSTEM ANALYSIS**

L	T	P	C
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OBJECTIVES:

- To model the power system under steady state operating condition
- To understand and apply iterative techniques for power flow analysis
- To model and carry out short circuit studies on power system
- To model and analyze stability problems in power system

UNIT I POWER SYSTEM 9

Need for system planning and operational studies - Power scenario in India - Power system components – Representation - Single line diagram - per unit quantities - p.u. impedance diagram - p.u. reactance diagram - Network graph, Bus incidence matrix, Primitive parameters, Bus admittance matrix from primitive parameters - Representation of off-nominal transformer - Formation of bus admittance matrix of large power network.

UNIT II POWER FLOW ANALYSIS 9

Bus classification - Formulation of Power Flow problem in polar coordinates - Power flow solution using Gauss Seidel method - Handling of Voltage controlled buses - Power Flow Solution by Newton Raphson method.

UNIT III SYMMETRICAL FAULT ANALYSIS 9

Assumptions in short circuit analysis - Symmetrical short circuit analysis using Thevenin's theorem - Bus Impedance matrix building algorithm (without mutual coupling) - Symmetrical fault analysis through bus impedance matrix - Post fault bus voltages - Fault level - Current limiting reactors.

UNIT IV UNSYMMETRICAL FAULT ANALYSIS 9

Symmetrical components - Sequence impedances - Sequence networks - Analysis of unsymmetrical faults at generator terminals: LG, LL and LLG - unsymmetrical fault occurring at any point in a power system - computation of post fault currents in symmetrical component and phasor domains.

UNIT V STABILITY ANALYSIS 9

Classification of power system stability – Rotor angle stability - Swing equation - Swing curve - Power-Angle equation - Equal area criterion - Critical clearing angle and time - Classical step-by-step solution of the swing equation – modified Euler method.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to model the power system under steady state operating condition
- Ability to understand and apply iterative techniques for power flow analysis
- Ability to model and carry out short circuit studies on power system
- Ability to model and analyze stability problems in power system
- Ability to acquire knowledge on Fault analysis.
- Ability to model and understand various power system components and carry out power flow, short circuit and stability studies.

TEXT BOOKS:

1. John J. Grainger, William D. Stevenson, Jr, 'Power System Analysis', Mc Graw Hill Education (India) Private Limited, New Delhi, 2015.
2. Kothari D.P. and Nagrath I.J., 'Power System Engineering', Tata McGraw-Hill Education, Second Edition, 2008.
3. Hadi Saadat, 'Power System Analysis', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 21st reprint, 2010.

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1. Pai M A, 'Computer Techniques in Power System Analysis', Tata Mc Graw-Hill Publishing Company Ltd., New Delhi, Second Edition, 2007.
2. J. Duncan Glover, Mulukutla S. Sarma, Thomas J. Overbye, 'Power System Analysis & Design', Cengage Learning, Fifth Edition, 2012.
3. Gupta B.R., 'Power System - Analysis and Design', S. Chand Publishing, 2001.
4. Kundur P., 'Power System Stability and Control', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 10th reprint, 2010.

EE8403 **MEASUREMENTS AND INSTRUMENTATION** **L T P C**
3 0 0 3

OBJECTIVES:

To impart knowledge on the following Topics

- Basic functional elements of instrumentation
- Fundamentals of electrical and electronic instruments
- Comparison between various measurement techniques
- Various storage and display devices
- Various transducers and the data acquisition systems

UNIT I INTRODUCTION **9**

Functional elements of an instrument – Static and dynamic characteristics – Errors in measurement – Statistical evaluation of measurement data – Standards and calibration- Principle and types of analog and digital voltmeters, ammeters.

UNIT II ELECTRICAL AND ELECTRONIC INSTRUMENTS **9**

Principle and types of multi meters – Single and three phase watt meters and energy meters – Magnetic measurements – Determination of B-H curve and measurements of iron loss – Instrument transformers – Instruments for measurement of frequency and phase.

UNIT III COMPARATIVE METHODS OF MEASUREMENTS **9**

D.C potentiometers, D.C (Wheat stone, Kelvin and Kelvin Double bridge) & A.C bridges (Maxwell, Anderson and Schering bridges), transformer ratio bridges, self-balancing bridges. Interference & screening – Multiple earth and earth loops - Electrostatic and electromagnetic Interference – Grounding techniques.

UNIT IV STORAGE AND DISPLAY DEVICES **9**

Magnetic disk and tape – Recorders, digital plotters and printers, CRT display, digital CRO, LED, LCD & Dot matrix display – Data Loggers.

UNIT V TRANSDUCERS AND DATA ACQUISITION SYSTEMS **9**

Classification of transducers – Selection of transducers – Resistive, capacitive & inductive Transducers – Piezoelectric, Hall effect, optical and digital transducers – Elements of data acquisition system – Smart sensors-Thermal Imagers.

TOTAL : 45 PERIODS

OUTCOMES:

- To acquire knowledge on Basic functional elements of instrumentation
- To understand the concepts of Fundamentals of electrical and electronic instruments
- Ability to compare between various measurement techniques
- To acquire knowledge on Various storage and display devices
- To understand the concepts Various transducers and the data acquisition systems
- Ability to model and analyze electrical and electronic Instruments and understand the operational features of display Devices and Data Acquisition System.

TEXT BOOKS:

1. A.K. Sawhney, 'A Course in Electrical & Electronic Measurements & Instrumentation', Dhanpat Rai and Co, 2010.
2. J. B. Gupta, 'A Course in Electronic and Electrical Measurements', S. K. Kataria & Sons, Delhi, 2013.
3. Doebelin E.O. and Manik D.N., Measurement Systems – Applications and Design, Special Indian Edition, McGraw Hill Education Pvt. Ltd., 2007.

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1. H.S. Kalsi, 'Electronic Instrumentation', McGraw Hill, III Edition 2010.
2. D.V.S. Murthy, 'Transducers and Instrumentation', Prentice Hall of India Pvt Ltd, 2015.
3. David Bell, ' Electronic Instrumentation & Measurements', Oxford University Press,2013.
4. Martin Reissland, 'Electrical Measurements', New Age International (P) Ltd., Delhi, 2001.
5. Alan. S. Morris, Principles of Measurements and Instrumentation, 2nd Edition, Prentice Hall of India, 2003.

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EE8016	ENERGY MANAGEMENT AND AUDITING	L	T	P	C
		3	0	0	3

OBJECTIVES: To impart knowledge about the following topics:

- To impact concepts behind economic analysis and Load management.
- Energy management on various electrical equipments and metering.
- Concept of lighting systems and cogeneration.

UNIT I INTRODUCTION 9

Basics of Energy – Need for energy management – Energy accounting - Energy monitoring, targeting and reporting - Energy audit process.

UNIT II ENERGY MANAGEMENT FOR MOTORS AND COGENERATION 9

Energy management for electric motors – Transformer and reactors - Capacitors and synchronous machines, energy management by cogeneration – Forms of cogeneration – Feasibility of cogeneration – Electrical interconnection.

UNIT III LIGHTING SYSTEMS 9

Energy management in lighting systems – Task and the working space - Light sources – Ballasts – Lighting controls – Optimizing lighting energy – Power factor and effect of harmonics, lighting and energy standards.

UNIT IV METERING FOR ENERGY MANAGEMENT 9

Metering for energy management – Units of measure - Utility meters – Demand meters – Paralleling of current transformers – Instrument transformer burdens – Multi tasking solid state meters, metering location vs requirements, metering techniques and practical examples.

UNIT V ECONOMIC ANALYSIS AND MODELS 9

Economic analysis – Economic models - Time value of money - Utility rate structures – Cost of electricity – Loss evaluation, load management – Demand control techniques – Utility monitoring and control system – HVAC and energy management – Economic justification.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to understand the basics of Energy audit process.
- Ability to understand the basics of energy management by cogeneration
- Ability to acquire knowledge on Energy management in lighting systems
- Ability to impact concepts behind economic analysis and Load management.
- Ability to understand the importance of Energy management on various electrical equipment and metering.
- Ability to acquire knowledge on HVAC.

TEXT BOOKS:

1. Barney L. Capehart, Wayne C. Turner, and William J. Kennedy, Guide to Energy Management, Fifth Edition, The Fairmont Press, Inc., 2006
2. Eastop T.D & Croft D.R, Energy Efficiency for Engineers and Technologists, Logman Scientific & Technical, ISBN-0-582-03184 , 1990.

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1. Reay D.A, Industrial Energy Conservation, 1st edition, Pergamon Press, 1977.
2. IEEE Recommended Practice for Energy Management in Industrial and Commercial Facilities, IEEE, 196.
3. Amit K. Tyagi, Handbook on Energy Audits and Management, TERI, 2003.
4. Electricity in buildings good practice guide, McGraw-Hill Education, 2016.
5. National Productivity Council Guide Books

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EE8251 **CIRCUIT THEORY**

L	T	P	C
2	2	0	3

OBJECTIVES:

- To introduce electric circuits and its analysis
- To impart knowledge on solving circuit equations using network theorems
- To introduce the phenomenon of resonance in coupled circuits.
- To educate on obtaining the transient response of circuits.
- To introduce Phasor diagrams and analysis of three phase circuits

UNIT I BASIC CIRCUITS ANALYSIS **6+6**

Resistive elements - Ohm's Law Resistors in series and parallel circuits – Kirchoffs laws – Mesh current and node voltage - methods of analysis.

UNIT II NETWORK REDUCTION AND THEOREMS FOR DC AND AC IRCUITS **6+6**

Network reduction: voltage and current division, source transformation – star delta conversion. Thevenins and Norton Theorems – Superposition Theorem – Maximum power transfer theorem – Reciprocity Theorem – Millman's theorem.

UNIT III TRANSIENT RESPONSE ANALYSIS **6+6**

L and C elements -Transient response of RL, RC and RLC Circuits using Laplace transform for DC input and A.C. sinusoidal input.

UNIT IV THREE PHASE CIRCUITS **6+6**

A.C. circuits – Average and RMS value - Phasor Diagram – Power, Power Factor and Energy.- Analysis of three phase 3-wire and 4-wire circuits with star and delta connected loads, balanced & un balanced – phasor diagram of voltages and currents – power measurement in three phase circuits.

UNIT V RESONANCE AND COUPLED CIRCUITS **6+6**

Series and parallel resonance – their frequency response – Quality factor and Bandwidth - Self and mutual inductance – Coefficient of coupling – Tuned circuits – Single tuned circuits.

TOTAL : 60 PERIODS

OUTCOMES:

- Ability to analyse electrical circuits
- Ability to apply circuit theorems
- Ability to analyse transients

TEXT BOOKS:

1. William H. Hayt Jr, Jack E. Kemmerly and Steven M. Durbin, "Engineering Circuits Analysis", McGraw Hill publishers, edition, New Delhi, 2013.
2. Charles K. Alexander, Mathew N.O. Sadiku, "Fundamentals of Electric Circuits", Second Edition, McGraw Hill, 2013.
3. Allan H. Robbins, Wilhelm C. Miller, "Circuit Analysis Theory and Practice", Cengage Learning India, 2013.

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2. Jegatheesan, R., "Analysis of Electric Circuits," McGraw Hill, 2015.
3. Joseph A. Edminister, Mahmood Nahri, "Electric circuits", Schaum's series, McGraw-Hill, New Delhi, 2010.
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5. Mahadevan, K., Chitra, C., "Electric Circuits Analysis," Prentice-Hall of India Pvt Ltd., New Delhi, 2015.
6. Richard C. Dorf and James A. Svoboda, "Introduction to Electric Circuits", 7th Edition, John Wiley & Sons, Inc. 2015.
7. Sudhakar A and Shyam Mohan SP, "Circuits and Network Analysis and Synthesis", McGraw Hill, 2015.

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EE8591 **DIGITAL SIGNAL PROCESSING**

L	T	P	C
2	2	0	3

OBJECTIVES: To impart knowledge about the following topics:

- Signals and systems & their mathematical representation.
- Discrete time systems.
- Transformation techniques & their computation.
- Filters and their design for digital implementation.
- Programmability digital signal processor & quantization effects.

UNIT I INTRODUCTION **6+6**

Classification of systems: Continuous, discrete, linear, causal, stability, dynamic, recursive, time variance; classification of signals: continuous and discrete, energy and power; mathematical representation of signals; spectral density; sampling techniques, quantization, quantization error, Nyquist rate, aliasing effect.

UNIT II DISCRETE TIME SYSTEM ANALYSIS **6+6**

Z-transform and its properties, inverse z-transforms; difference equation – Solution by z-transform, application to discrete systems - Stability analysis, frequency response – Convolution – Discrete Time Fourier transform , magnitude and phase representation.

UNIT III DISCRETE FOURIER TRANSFORM & COMPUTATION **6+6**

Discrete Fourier Transform- properties, magnitude and phase representation - Computation of DFT using FFT algorithm – DIT &DIF using radix 2 FFT – Butterfly structure.

UNIT IV DESIGN OF DIGITAL FILTERS **6+6**

FIR & IIR filter realization – Parallel & cascade forms. FIR design: Windowing Techniques – Need and choice of windows – Linear phase characteristics. Analog filter design – Butterworth and Chebyshev approximations; IIR Filters, digital design using impulse invariant and bilinear transformation Warping, pre warping.

UNIT V DIGITAL SIGNAL PROCESSORS **6+6**

Introduction – Architecture – Features – Addressing Formats – Functional modes - Introduction to Commercial DS Processors.

TOTAL : 60 PERIODS

OUTCOMES:

1. Ability to understand the importance of Fourier transform, digital filters and DS Processors.
2. Ability to acquire knowledge on Signals and systems & their mathematical representation.
3. Ability to understand and analyze the discrete time systems.
4. Ability to analyze the transformation techniques & their computation.
5. Ability to understand the types of filters and their design for digital implementation.
6. Ability to acquire knowledge on programmability digital signal processor & quantization effects.

TEXT BOOKS:

1. J.G. Proakis and D.G. Manolakis, 'Digital Signal Processing Principles, Algorithms and Applications', Pearson Education, New Delhi, PHI. 2003.
2. S.K. Mitra, 'Digital Signal Processing – A Computer Based Approach', McGraw Hill Edu, 2013.
3. Lonnie C.Ludeman ,"Fundamentals of Digital Signal Processing",Wiley,2013

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1. Poorna Chandra S, Sasikala. B ,Digital Signal Processing, Vijay Nicole/TMH,2013.
2. Robert Schilling & Sandra L.Harris, Introduction to Digital Signal Processing using Matlab", Cengage Learning,2014.
3. B.P.Lathi, 'Principles of Signal Processing and Linear Systems', Oxford University Press, 2010 3. Taan S. ElAli, 'Discrete Systems and Digital Signal Processing with Mat Lab', CRC Press, 2009.
4. SenM.kuo, woonseng…s.gan, "Digital Signal Processors, Architecture, Implementations & Applications, Pearson,2013
5. DimitrisG.Manolakis, Vinay K. Ingle, applied Digital Signal Processing,Cambridge,2012

EC8395 **COMMUNICATION ENGINEERING** L T P C
3 0 0 3

OBJECTIVES:

- To introduce the relevance of this course to the existing technology through demonstrations, case studies, simulations, contributions of scientist, national/international policies with a futuristic vision along with socio-economic impact and issues
- To study the various analog and digital modulation techniques
- To study the principles behind information theory and coding
- To study the various digital communication techniques

UNIT I ANALOG MODULATION 9

Amplitude Modulation – AM, DSBSC, SSBSC, VSB – PSD, modulators and demodulators – Angle modulation – PM and FM – PSD, modulators and demodulators – Superheterodyne receivers

UNITII PULSE MODULATION 9

Low pass sampling theorem – Quantization – PAM – Line coding – PCM, DPCM, DM, and ADPCM And ADM, Channel Vocoder - Time Division Multiplexing, Frequency Division Multiplexing

UNIT III DIGITAL MODULATION AND TRANSMISSION 9

Phase shift keying – BPSK, DPSK, QPSK – Principles of M-ary signaling M-ary PSK & QAM – Comparison, ISI – Pulse shaping – Duo binary encoding – Cosine filters – Eye pattern, equalizers

UNIT IV INFORMATION THEORY AND CODING 9

Measure of information – Entropy – Source coding theorem – Shannon–Fano coding, Huffman Coding, LZ Coding – Channel capacity – Shannon-Hartley law – Shannon's limit – Error control codes – Cyclic codes, Syndrome calculation – Convolution Coding, Sequential and Viterbi decoding

UNIT V SPREAD SPECTRUM AND MULTIPLE ACCESS 9

PN sequences – properties – m-sequence – DSSS – Processing gain, Jamming – FHSS – Synchronisation and tracking – Multiple Access – FDMA, TDMA, CDMA,

TOTAL: 45 PERIODS

OUTCOMES:

At the end of the course, the student should be able to:

- Ability to comprehend and appreciate the significance and role of this course in the present contemporary world
- Apply analog and digital communication techniques.
- Use data and pulse communication techniques.
- Analyze Source and Error control coding.

TEXT BOOKS:

1. H Taub, D L Schilling, G Saha, "Principles of Communication Systems" 3/e, TMH 2007
2. S. Haykin "Digital Communications" John Wiley 2005

REFERENCES:

1. B.P.Lathi, "Modern Digital and Analog Communication Systems", 3rd edition, Oxford University Press, 2007
2. H P Hsu, Schaum Outline Series – "Analog and Digital Communications" TMH 2006
3. B.Sklar, Digital Communications Fundamentals and Applications" 2/e Pearson Education 2007.

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WEB MONITORING AND SPEED CONTROL OF BLDC MOTOR WITH IoT

A PROJECT REPORT

Submitted by

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KHAJA MOHIDEEN.MAF	**(311817105302)**
MOHAMED NIHATH.N	**(311817105007)**

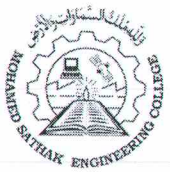
in partial fulfilment for the award of the degree

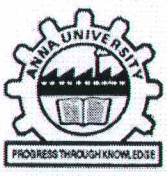
of

BACHELOR OF ENGINEERING

in

DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING





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MARCH 2021

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ANNA UNIVERSITY : CHENNAI 600 025

BONAFIDE CERTIFICATE

Certified that this project report "**WEB MONITORING AND SPEED CONTROL OF BLDC MOTOR WITH IoT**" is the bonafide work of **K.HASSAIN (311817105301), MAF.KHAJA MOHIDEEN(311817105302), N.MOHAMED NIHATH(311817105007)** who carried out the project work under my supervision.

SIGNATURE

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Assistant Professor

Department of Electrical and Electronic Engineering

Mohamed Sathak A.J college of Engineering , Chennai-603103

SIGNATURE

Mrs.H. Brindha M.E.,
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Assistant Professor

Department of Electrical and Electronics Engineering

Mohamed Sathak A.J college of Engineering , Chennai-603103

Project Viva-Voce held on 6/8/21

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INTERNAL EXAMINER

EXTERNAL EXAMINER

ABSTRACT

This Project Proposes the Web Monitoring of Brushless Direct Current(BLDC)motor and its Speed control is done with Closed loop Technique. Brushless DC motor is an emerging trend in Industrial Applications due to its domination over the motors with Counterparts. The hardware setup is made with a part of Controller The BLDC motor speed can be controlled with low cost atmel 328p microcontroller . We have employed microcontroller and programmed with Embedded C in order to vary the duty cycle of motor. The Communication module which is used in order to monitor the working state of the machine is done with Internet of Things (IoT). The Industrial Persons can monitor the parameters using IoT provided with Unique Login credentials which comes under the proposed system.

Keywords : Speed Control,IoT,BLDC

CHAPTER 5

CONCLUSION AND REFERENCE

5.1 CONCLUSION

The proposed system will help the Industrial people to monitor the BLDC motor from their remote location itself. The speed of the motor is controlled with the help of PWM technique and it is made to run at the required or desired speed. Monitoring is done with the help of Internet of Things (IoT).Internet of Things (IoT) plays major role in this system. The communication is made healthier and stronger with the help of this communication module. This brings advantages and has a good scope for Industries. Thus the proposed method is very well suited for Industrial applications

5.2 REFERENCE

[1] Sreeramk ,"Design of Fuzzy Logic Controller for Speed Control of Sensor less BLDC Motor Drive", IEE International Conference On Control, Power , Communication and computing Technologies, pp 18- 24,2018.

[2] K.S. Krishna Veni; Dr.N.Senthil Kumar; J.Gnanavadivel, "Low Cost Fuzzy Logic Based Speed Control Of BLDC Motor", IEEE International Conference On Advances In Electrical Technology For Green Energy, pp 1-5, 2017.

[3] K.Sowmiya;R.VishnuPriya, "Microcontroller Based Speed Control Scheme of BLDC Motor Using Proteus", International Journal, Volume: 5, Issue: III,2017.

[4] Rodolfo L Valle ;Pedro M.de Almeida ;Andre A. Ferreira; Pedro G. Barbosa, " Unipolar PWM Predictive Current–mode Control Of Variable-Speed Low inductance BLDC Motor drive", Volume:11, Issue: 5,pp 688696,2017.

DESIGN AND DEVELOPEMENT OF DUAL AXIS CONTROLLED WRITING ROBOT FOR PRESCRIPTION WRITING

A PROJECT REPORT

Submitted by

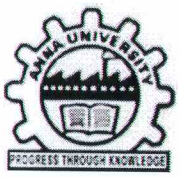
IJAZ AHAMED.M (311817105003),
MOHAMED AMRITH.U (311817105004).

in partial fulfillment for the award of the degreeof

BACHELOR OF ENGINEERING

IN

ELECTRICAL AND ELECTRONICS ENGINEERING



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MARCH 2021

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BONAFIDE CERTIFICATE

Certified that this project report "**DESIGN AND DEVELOPMENT OF DUAL AXIS CONTROLLED WRITING ROBOT FOR PRESCRIPTION WRITING**" is the bonafide work of **U.MOHAMED AMRITH (311817105004), I.IJAZ AHAMED (311817105003),** who carried out the project work under my supervision.

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Project Viva-Voce held on....6/8/21..

INTERNAL EXAMINAR

EXTERNAL EXAMINAR

ABSTRACT

The main aim of this project is to develop a writing robot in order to help the education system to make more interesting by speech recognition technique. In which visual basic software is used in this system. Speech recognition has been implemented using arduino microcontroller (ATMEGA328). It has been used to control the robotic arm by servo motor based on the user's input. Robots have been used in various industries like medical, science, research etc. So in this paper a new idea has been proposed to implement robots in education.The paper presents an approach to design rapid and fluid movements of a universal robot to perform robot writing. In existing system, the input for the writing robot should be in G-Code or M-Code which is nothing but machine level language. Machine level language would be pretty difficult to understand the data. In proposed system it becomes more easier than the existing system, the input data can be in normal English wording, so that the complier can convert the normal wording into machine level language.To perform the task, on-line human signing standards are created first. Robot writing task is performed using these standards after that and robot signatures are acquired as a result. Finally, recommendations of robot motion improvement are given.

Keywords— *writing robot, human writing, robot writing ,control Mimicking functions*

```
      }
     }
     if (servo06SP[i] < servo06SP[i + 1]) {
      for ( int j = servo06SP[i]; j <= servo06SP[i + 1]; j++) {
       servo06.write(j);
       delay(speedDelay);
      }
     }
    }
   }
}
```

14 CONCLUSION

Interaction between human and machine is an important factor of developing a technology of Speech recognition. This robotic arm was successfully trained to recognize speech inputs that were recorded using a microphone as well as speech sample obtained from the database.

ACKNOWLEDGEMENT

We would like to thank to our Department of Electronics and Communication Engineering, Dhaanish ahmed college of engineering for their guidance and support.

15 REFERENCES

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[3] M. C. Lau and J. Baltes, "The real-time embedded system for a humanoid: Betty," in Proceedings of the 13th FIRA Robot World Congress, vol. 103 of

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B.E – ELECTRONICS AND COMMUNICATION ENGINEERING

S.NO	Name of the course that include experiential learning through Project work/ Internship	Page No
1	EC8093- Digital Image Processing	
2	EC8073- Medical Electronics	
3	EC8553- Discrete-Time Signal Processing	
4	EC8791- Embedded and Real Time Systems	
5	EC8004 -Wireless Networks	
6	EC8652 -Wireless Communication	
7	EC8393 -Fundamentals of Data Structure in C	
8	OCS752 -Introduction to C Programming	
9	EC8691 -Microprocessor and Microcontroller	
10	EC8352- Signals and Systems	
11	GE8291 -Environmental Science and Engineering	
12	EC8391- Control System Engineering	
13	EC8252 -Electronic Devices	
14	EC8702- Ad hoc and Wireless Sensor Networks	
15	EC8551- Communication Networks	
16	BE8254- Basic Electrical and Instrumentation Engineering	

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