MOHAMED SATHAK A J COLLEGE OF ENGINEERING

Sponsored by Mohamed Sathak Trust

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Siruseri IT Park, Egattur, Chennai 603 103

S.No	Name of the course that include experimental learning through Project Work/Internship/Mini Project 2017-2018
1	EE6402-Transmission and Distribution
2	EE6503-Power Electronics
3	EE6009-Power Electronics for Renewable Energy Systems
4	ME6701-Power Plant Engineering
5	EE6007-Micro Electro Mechanical Systems
6	EE6703-Special Electrical Machines
7	EE6002-Power System Transients
8	EE6003-Optimisation Techniques
9	EC6002-Advanced Digital Signal Processing
10	EE6801-Electric Energy Generation,Utilization and Conservation
11	EE6502-Microprocessors and Microcontrollers
12	EE6001-Visual Language and Application
13	EI6704-Biomedical Instrumentation

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S.No.	Subject Code	Subject Name	Contents that included Experimental Learning through Project Work
1	EE6402	Transmission and Distribution	Grading of Cables Substation Layout (AIS, GIS)

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EE6402 **TRANSMISSION AND DISTRIBUTION** **LT P C**
3 0 0 3

OBJECTIVES:

- To develop expressions for the computation of transmission line parameters.
- To obtain the equivalent circuits for the transmission lines based on distance and operating
- voltage for determining voltage regulation and efficiency. Also to improve the voltage profile of the transmission system.
- To analyses the voltage distribution in insulator strings and cables and methods to improvethe same.
- To understand the operation of the different distribution schemes.

UNIT I STRUCTURE OF POWER SYSTEM **9**

Structure of electric power system: generation, transmission and distribution; Types of AC and DC distributors – distributed and concentrated loads – interconnection – EHVAC and HVDC transmission - Introduction to FACTS.

UNIT II TRANSMISSION LINE PARAMETERS **9**

Parameters of single and three phase transmission lines with single and double circuits - Resistance, inductance and capacitance of solid, stranded and bundled conductors, Symmetrical and unsymmetrical spacing and transposition - application of self and mutual GMD; skin and proximity effects - interference with neighboring communication circuits - Typical configurations, conductor types and electrical parameters of EHV lines, corona discharges.

UNIT III MODELLING AND PERFORMANCE OF TRANSMISSION LINES **9**

Classification of lines - short line, medium line and long line - equivalent circuits, phasor diagram, attenuation constant, phase constant, surge impedance; transmission efficiency and voltage regulation, real and reactive power flow in lines, Power - circle diagrams, surge impedance loading, methods of voltage control; Ferranti effect.

UNIT IV INSULATORS AND CABLES **9**

Insulators - Types, voltage distribution in insulator string, improvement of string efficiency, testing of insulators. Underground cables - Types of cables, Capacitance of Single-core cable, Grading of cables, Power factor and heating of cables, Capacitance of 3- core belted cable, D.C cables.

UNIT V MECHANICAL DESIGN OF LINES AND GROUNDING **9**

Mechanical design of transmission line – sag and tension calculations for different weather conditions, Tower spotting, Types of towers, Substation Layout (AIS, GIS), Methods of grounding.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to understand and analyze power system operation, stability, control and protection.

TEXT BOOKS:

1. D.P.Kothari , I.J. Nagarath, 'Power System Engineering', Tata McGraw-Hill Publishing Company limited, New Delhi, Second Edition, 2008.
2. C.L.Wadhwa, 'Electrical Power Systems', New Academic Science Ltd, 2009.
3. S.N. Singh, 'Electric Power Generation, Transmission and Distribution', Prentice Hall of India Pvt. Ltd, New Delhi, Second Edition, 2011.

REFERENCES:

1. B.R.Gupta, , S.Chand, 'Power System Analysis and Design'New Delhi, Fifth Edition, 2008.
2. Luces M.Fualken berry ,Walter Coffer, 'Electrical Power Distribution and Transmission', Pearson Education, 2007.
3. Hadi Saadat, 'Power System Analysis,' PSA Publishing; Third Edition, 2010.
4. J.Brian, Hardy and Colin R.Bayliss 'Transmission and Distribution in Electrical Engineering', Newnes; Fourth Edition, 2012.
5. G.Ramamurthy, "Handbook of Electrical power Distribution," Universities Press, 2013.

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S.No.	Subject Code	Subject Name	Contents that include Experimental Learning through Project Work
2	EE6503	Power Electronics	Three phase voltage source inverters Current source inverter.

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EE6503 **POWER ELECTRONICS** **L T P C**
3 0 0 3

OBJECTIVES:

- To get an overview of different types of power semiconductor devices and their switching characteristics.
- To understand the operation, characteristics and performance parameters of controlled rectifiers
- To study the operation, switching techniques and basics topologies of DC-DC switching regulators.
- To learn the different modulation techniques of pulse width modulated inverters and to understand harmonic reduction methods.
- To study the operation of AC voltage controller and various configurations.

UNIT I POWERSEMI-CONDUCTOR DEVICES **9**

Study of switching devices, Diode, SCR,TRIAC, GTO, BJT, MOSFET, IGBT-Static and Dynamic characteristics - Triggering and commutation circuit for SCR- Design of Driver and snubber circuit.

UNIT II PHASE-CONTROLLED CONVERTERS **9**

2-pulse,3-pulse and 6-pulseconverters– performance parameters –Effect of source inductance— Gate Circuit Schemes for Phase Control–Dual converters.

UNIT III DC TO DC CONVERTER **9**

Step-down and step-up chopper-control strategy–Forced commutated chopper–Voltage commutated, Current commutated, Load commutated, Switched mode regulators- Buck, boost, buck- boost converter, Introduction to Resonant Converters.

UNIT IV INVERTERS **9**

Single phase and three phase voltage source inverters(both 120^0modeand 180^0mode)–Voltage& harmonic control--PW M techniques: Sinusoidal PWM, modified sinusoidal PWM - multiple PWM – Introduction to space vector modulation –Current source inverter.

UNIT V AC TO AC CONVERTERS **9**

Single phase and Three phase AC voltage controllers–Control strategy- Power Factor Control – Multistage sequence control -single phase and three phase cyclo converters –Introduction to Matrix converters.

TOTAL:45 PERIODS

OUTCOMES:

- Ability to understand and analyse, linear and digital electronic circuits.

TEXT BOOKS:

1. M.H.Rashid, 'Power Electronics: Circuits, Devices and Applications', Pearson Education, PHI Third Edition, New Delhi, 2004.
2. P.S.Bimbra "Power Electronics" Khanna Publishers, third Edition, 2003.
3. L. Umanand, " Power Electronics Essentials and Applications", Wiley, 2010.

REFERENCES:

1. Joseph Vithayathil,' Power Electronics, Principles and Applications', McGraw Hill Series, 6th Reprint, 2013.
2. Ashfaq Ahmed Power Electronics for Technology Pearson Education, Indian reprint, 2003.
3. Philip T. Krein, "Elements of Power Electronics" Oxford University Press, 2004 Edition.
4. Ned Mohan, Tore. M. Undel and, William. P. Robbins,' Power Electronics: Converters, Applications and Design', John Wiley and sons, third edition,2003.
5. Daniel.W.Hart, "Power Electronics", Indian Edition, Mc Graw Hill, 3rd Print, 2013.
6. M.D. Singh and K.B. Khanchandani, "Power Electronics," Mc Graw Hill India, 2013.

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S.No.	Subject Code	Subject Name	Contents that included experimental learning through Project Work
3	EE6009	Power Electronics for Renewable Energy Systems	Qualitative study of different renewable energy resources Range and type of Hybrid systems

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EE6009 **POWER ELECTRONICS FOR RENEWABLE ENERGY SYSTEMS** **LT P C 3 0 0 3**

OBJECTIVES:

- To Provide knowledge about the stand alone and grid connected renewable energy systems.
- To equip with required skills to derive the criteria for the design of power converters for renewable energy applications.
- To analyse and comprehend the various operating modes of wind electrical generators and solar energy systems.
- To design different power converters namely AC to DC, DC to DC and AC to AC converters for renewable energy systems.
- To develop maximum power point tracking algorithms.

UNIT I INTRODUCTION **9**

Environmental aspects of electric energy conversion: impacts of renewable energy generation on environment (cost-GHG Emission) - Qualitative study of different renewable energy resources: Solar, wind, ocean, Biomass, Fuel cell, Hydrogen energy systems and hybrid renewable energy systems.

UNIT II ELECTRICAL MACHINES FOR RENEWABLE ENERGY CONVERSION **9**

Reference theory fundamentals-principle of operation and analysis: IG, PMSG, SCIG and DFIG.

UNIT III POWER CONVERTERS **9**

Solar: Block diagram of solar photo voltaic system -Principle of operation: line commutated converters (inversion-mode) - Boost and buck-boost converters- selection of inverter, battery sizing, array sizing Wind: Three phase AC voltage controllers- AC-DC-AC converters: uncontrolled rectifiers, PWM Inverters, Grid Interactive Inverters-matrix converters.

UNIT IV ANALYSIS OF WIND AND PV SYSTEMS **9**

Stand alone operation of fixed and variable speed wind energy conversion systems and solar system-Grid connection Issues -Grid integrated PMSG, SCIG Based WECS, grid Integrated solar system

UNIT V HYBRID RENEWABLE ENERGY SYSTEMS **9**

Need for Hybrid Systems- Range and type of Hybrid systems- Case studies of Wind-PV Maximum Power Point Tracking (MPPT).

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to understand and analyze power system operation, stability, control and protection.
- Ability to handle the engineering aspects of electrical energy generation and utilization.

TEXT BOOK:

1. S. N. Bhadra, D.Kastha, S.Banerjee, "Wind Electrical Systems", Oxford University Press, 2005.
2. B.H.Khan Non-conventional Energy sources Tata McGraw-hill Publishing Company, New Delhi,2009.

REFERENCES:

1. Rashid .M. H "power electronics Hand book", Academic press, 2001.
2. Ion Boldea, "Variable speed generators", Taylor & Francis group, 2006.
3. Rai. G.D, "Non conventional energy sources", Khanna publishes, 1993.
4. Gray, L. Johnson, "Wind energy system", prentice hall linc, 1995.
5. Andrzej M. Trzynnadlowski, 'Introduction to Modern Power Electronics', Second edition, wiley India Pvt. Ltd, 2012.

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S.No.	Subject Code	Subject Name	Contents that included experimental learning through Project Work
4	ME6701	Power Plant Engineering	Solar Photo Voltaic (SPV), Fuel Cell power systems

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ME6701 **POWER PLANT ENGINEERING** **L T P C**
3 0 0 3

OBJECTIVES:

- Providing an overview of Power Plants and detailing the role of Mechanical Engineers in their operation and maintenance.

UNIT I COAL BASED THERMAL POWER PLANTS **10**

Rankine cycle - improvisations, Layout of modern coal power plant, Super Critical Boilers, FBC Boilers, Turbines, Condensers, Steam & Heat rate, Subsystems of thermal power plants – Fuel and ash handling, Draught system, Feed water treatment. Binary Cycles and Cogeneration systems.

UNIT II DIESEL, GAS TURBINE AND COMBINED CYCLE POWER PLANTS **10**

Otto, Diesel, Dual & Brayton Cycle - Analysis & Optimisation. Components of Diesel and Gas Turbine power plants. Combined Cycle Power Plants. Integrated Gasifier based Combined Cycle systems.

UNIT III NUCLEAR POWER PLANTS **7**

Basics of Nuclear Engineering, Layout and subsystems of Nuclear Power Plants, Working of Nuclear Reactors : *Boiling Water Reactor* (BWR), *Pressurized Water Reactor* (PWR), CANada Deuterium- Uranium reactor (CANDU), Breeder, Gas Cooled and Liquid Metal Cooled Reactors. Safety measures for Nuclear Power plants.

UNIT IV POWER FROM RENEWABLE ENERGY **10**

Hydro Electric Power Plants – Classification, Typical Layout and associated components including Turbines. Principle, Construction and working of Wind, Tidal, *Solar* Photo Voltaic (SPV), Solar Thermal, Geo Thermal, Biogas and Fuel Cell power systems.

UNIT V ENERGY, ECONOMIC AND ENVIRONMENTAL ISSUES OF POWER PLANTS **8**

Power tariff types, Load distribution parameters, load curve, Comparison of site selection criteria, relative merits & demerits, Capital & Operating Cost of different power plants. Pollution control technologies including Waste Disposal Options for Coal and Nuclear Power Plants.

TOTAL : 45 PERIODS

OUTCOMES:

- Upon completion of this course, the Students can able to understand different types of power plant, and its functions and their flow lines and issues related to them.
- Analyse and solve energy and economic related issues in power sectors.

TEXT BOOK:

1. P.K. Nag, Power Plant Engineering, Tata McGraw – Hill Publishing Company Ltd., Third Edition, 2008.

REFERENCES:

1. M.M. El-Wakil, Power Plant Technology, Tata McGraw – Hill Publishing Company Ltd., 2010.
2. Black & Veatch, Springer, Power Plant Engineering, 1996.
3. Thomas C. Elliott, Kao Chen and Robert C. Swanekamp, Standard Handbook of Power Plant Engineering, Second Edition, McGraw – Hill, 1998.
4. Godfrey Boyle, Renewable energy, Open University, Oxford University Press in association with the Open University, 2004.

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S.No.	Subject Code	Subject Name	Contents that included experimental learning through Project Work
5	EE6007	Micro Electro Mechanical Systems	Review of Electrical and Mechanical concepts in MEMS Electrostatic sensors

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EE6007 **MICRO ELECTRO MECHANICAL SYSTEMS** **L T P C**
3 0 0 3

OBJECTIVES:

- To provide knowledge of semiconductors and solid mechanics to fabricate MEMS devices.
- To educate on the rudiments of Micro fabrication techniques.
- To introduce various sensors and actuators
- To introduce different materials used for MEMS
- To educate on the applications of MEMS to disciplines beyond Electrical and Mechanical engineering.

UNIT I INTRODUCTION **9**

Intrinsic Characteristics of MEMS – Energy Domains and Transducers- Sensors and Actuators – Introduction to Micro fabrication - Silicon based MEMS processes – New Materials – Review of Electrical and Mechanical concepts in MEMS – Semiconductor devices – Stress and strain analysis – Flexural beam bending- Torsional deflection.

UNIT II SENSORS AND ACTUATORS-I **9**

Electrostatic sensors – Parallel plate capacitors – Applications – Interdigitated Finger capacitor – Comb drive devices – Micro Grippers – Micro Motors - Thermal Sensing and Actuation – Thermal expansion – Thermal couples – Thermal resistors – Thermal Bimorph - Applications – Magnetic Actuators – Micromagnetic components – Case studies of MEMS in magnetic actuators- Actuation using Shape Memory Alloys.

UNIT III SENSORS AND ACTUATORS-II **9**

Piezoresistive sensors – Piezoresistive sensor materials - Stress analysis of mechanical elements – Applications to Inertia, Pressure, Tactile and Flow sensors – Piezoelectric sensors and actuators – piezoelectric effects – piezoelectric materials – Applications to Inertia , Acoustic, Tactile and Flow sensors.

UNIT IV MICROMACHINING **9**

Silicon Anisotropic Etching – Anisotrophic Wet Etching – Dry Etching of Silicon – Plasma Etching – Deep Reaction Ion Etching (DRIE) – Isotropic Wet Etching – Gas Phase Etchants – Case studies - Basic surface micro machining processes – Structural and Sacrificial Materials – Acceleration of sacrificial Etch – Striction and Antistriction methods – LIGA Process - Assembly of 3D MEMS – Foundry process.

UNIT V POLYMER AND OPTICAL MEMS **9**

Polymers in MEMS– Polimide - SU-8 - Liquid Crystal Polymer (LCP) – PDMS – PMMA – Parylene – Fluorocarbon - Application to Acceleration, Pressure, Flow and Tactile sensors- Optical MEMS – Lenses and Mirrors – Actuators for Active Optical MEMS.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to understand the operation of micro devices, micro systems and their applications.
- Ability to design the micro devices, micro systems using the MEMS fabrication process.

TEXT BOOKS:

1. Chang Liu, 'Foundations of MEMS', Pearson Education Inc., 2012.
2. Stephen D Senturia, 'Microsystem Design', Springer Publication, 2000.
3. Tai Ran Hsu, "MEMS & Micro systems Design and Manufacture" Tata McGraw Hill, New Delhi, 2002.

REFERENCES:

1. Nadim Maluf," An Introduction to Micro Electro Mechanical System Design", Artech House, 2000.
2. Mohamed Gad-el-Hak, editor, " The MEMS Handbook", CRC press Baco Raton, 2001.
3. Julian w. Gardner, Vijay K. Varadan, Osama O.Awadelkarim, "Micro Sensors, MEMS and Smart Devices, John Wiley & Son LTD, 2002.
4. James J.Allen, Micro Electro Mechanical System Design, CRC Press Publisher, 2005.
5. Thomas M.Adams and Richard A.Layton, "Introduction MEMS, Fabrication and Application," Springer, 2010.

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S.No.	Subject Code	Subject Name	Contents that included Experimental Learning through Project Work
6	EE6703	Special Electrical Machines	Sensor less operation Converter Volt-Ampere requirements

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EE6703 **SPECIAL ELECTRICAL MACHINES** **LT P C 3 0 0 3**

OBJECTIVES:

- To impart knowledge on Construction, principle of operation and performance of synchronous reluctance motors.
- To impart knowledge on the Construction, principle of operation, control and performance of stepping motors.
- To impart knowledge on the Construction, principle of operation, control and performance of switched reluctance motors.
- To impart knowledge on the Construction, principle of operation, control and performance of permanent magnet brushless D.C. motors.
- To impart knowledge on the Construction, principle of operation and performance of permanent magnet synchronous motors.

UNIT I SYNCHRONOUS RELUCTANCE MOTORS **9**

Constructional features – Types – Axial and Radial flux motors – Operating principles – Variable Reluctance Motors – Voltage and Torque Equations - Phasor diagram - performance characteristics – Applications.

UNIT II STEPPER MOTORS **9**

Constructional features – Principle of operation – Variable reluctance motor – Hybrid motor – Single and multi stack configurations – Torque equations – Modes of excitation – Characteristics – Drive circuits – Microprocessor control of stepper motors – Closed loop control-Concept of lead angle– Applications.

UNIT III SWITCHED RELUCTANCE MOTORS (SRM) **9**

Constructional features – Rotary and Linear SRM - Principle of operation – Torque production – Steady state performance prediction- Analytical method -Power Converters and their controllers –Methods of Rotor position sensing – Sensor less operation – Characteristics and Closed loop control – Applications.

UNIT IV PERMANENT MAGNET BRUSHLESS D.C. MOTORS **9**

Permanent Magnet materials – Minor hysteresis loop and recoil line-Magnetic Characteristics – Permeance coefficient -Principle of operation – Types – Magnetic circuit analysis – EMF and torque equations –Commutation - Power Converter Circuits and their controllers – Motor characteristics and control– Applications.

UNIT V PERMANENT MAGNET SYNCHRONOUS MOTORS (PMSM) **9**

Principle of operation – Ideal PMSM – EMF and Torque equations – Armature MMF – Synchronous Reactance – Sine wave motor with practical windings - Phasor diagram – Torque/speed characteristics - Power controllers - Converter Volt-ampere requirements– Applications.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to model and analyze electrical apparatus and their application to power system

TEXT BOOKS:

1. K.Venkataratnam, 'Special Electrical Machines', Universities Press (India) Private Limited, 2008.
2. T.J.E. Miller, 'Brushless Permanent Magnet and Reluctance Motor Drives', Clarendon Press, Oxford, 1989.
3. T. Kenjo, 'Stepping Motors and Their Microprocessor Controls', Clarendon Press London, 1984.

REFERENCES:

1. R.Krishnan, 'Switched Reluctance Motor Drives – Modeling, Simulation, Analysis, Design and Application', CRC Press, New York, 2001.
2. P.P. Aearnley, 'Stepping Motors – A Guide to Motor Theory and Practice', Peter Perengrinus London, 1982.
3. T. Kenjo and S. Nagamori, 'Permanent Magnet and Brushless DC Motors', Clarendon Press, London, 1988.
4. E.G. Janardanan, 'Special electrical machines', PHI learning Private Limited, Delhi, 2014.

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S.No.	Subject Code	Subject Name	Contents that included Experimental Learning through Project Work
7	EE6002	Power System Transients	Formation of clouds and charge formation over voltage induced by faults

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EE6002 **POWER SYSTEM TRANSIENTS** LT P C 3 0 0 3

OBJECTIVES:

- To study the generation of switching transients and their control using circuit – theoretical concept.
- To study the mechanism of lighting strokes and the production of lighting surges.
- To study the propagation, reflection and refraction of travelling waves.
- To study the impact of voltage transients caused by faults, circuit breaker action, load rejection on integrated power system.

UNIT I INTRODUCTION AND SURVEY 9

Review and importance of the study of transients - causes for transients. RL circuit transient with sine wave excitation - double frequency transients - basic transforms of the RLC circuit transients. Different types of power system transients - effect of transients on power systems – role of the study of transients in system planning.

UNIT II SWITCHING TRANSIENTS 9

Over voltages due to switching transients - resistance switching and the equivalent circuit for interrupting the resistor current - load switching and equivalent circuit - waveforms for transient voltage across the load and the switch - normal and abnormal switching transients. Current suppression - current chopping - effective equivalent circuit. Capacitance switching - effect of source regulation - capacitance switching with a restrike, with multiple restrikes. Illustration for multiple restriking transients - ferro resonance.

UNIT III LIGHTNING TRANSIENTS 9

Review of the theories in the formation of clouds and charge formation - rate of charging of thunder clouds – mechanism of lightning discharges and characteristics of lightning strokes – model for lightning stroke - factors contributing to good line design - protection using ground wires - tower footing resistance - Interaction between lightning and power system.

UNIT IV TRAVELING WAVES ON TRANSMISSION LINE COMPUTATION OF TRANSIENTS 9

Computation of transients - transient response of systems with series and shunt lumped parameters and distributed lines. Traveling wave concept - step response - Bewely's lattice diagram - standing waves and natural frequencies - reflection and refraction of travelling waves.

UNIT V TRANSIENTS IN INTEGRATED POWER SYSTEM 9

The short line and kilometric fault - distribution of voltages in a power system - Line dropping and load rejection - voltage transients on closing and reclosing lines - over voltage induced by faults -switching surges on integrated system Qualitative application of EMTP for transient computation.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to understand and analyze power system operation, stability, control and protection.

TEXT BOOKS:

1. Allan Greenwood, 'Electrical Transients in Power Systems', Wiley Inter Science, New York, 2nd Edition, 1991.
2. Pritindra Chowdhari, "Electromagnetic transients in Power System", John Wiley and Sons Inc., Second Edition, 2009.
3. C.S. Indulkar, D.P.Kothari, K. Ramalingam, 'Power System Transients – A statistical approach', PHI Learning Private Limited, Second Edition, 2010.

REFERENCES:

1. M.S.Naidu and V.Kamaraju, 'High Voltage Engineering', Tata McGraw Hill, Fifth Edition, 2013.
2. R.D. Begamudre, 'Extra High Voltage AC Transmission Engineering', Wiley Eastern Limited, 1986.
3. Y.Hase, Handbook of Power System Engineering," Wiley India, 2012.
4. J.L.Kirtley, "Electric Power Principles, Sources, Conversion, Distribution and use," Wiley, 2012.

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S.No.	Subject Code	Subject Name	Contents that included experimental learning through Project Work
8	EE6003	Optimization Techniques	Duality theory Formulation of Multi stage decision problem

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EE6003 **OPTIMISATION TECHNIQUES** L T P C
3 0 0 3

OBJECTIVES:

- To introduce the basic concepts of linear programming
- To educate on the advancements in Linear programming techniques
- To introduce non-linear programming techniques
- To introduce the interior point methods of solving problems
- To introduce the dynamic programming method

UNIT I LINEAR PROGRAMMING 9

Introduction - formulation of linear programming model-Graphical solution–solving LPP using simplex algorithm – Revised Simplex Method.

UNIT II ADVANCES IN LPP 9

Dualit theory- Dual simplex method - Sensitivity analysis—Transportation problems–Assignment problems-Traveling sales man problem -Data Envelopment Analysis.

UNIT III NON LINEAR PROGRAMMING 9

Classification of Non Linear programming – Lagrange multiplier method – Karush – Kuhn Tucker conditions–Reduced gradient algorithms–Quadratic programming method – Penalty and Barrier method.

UNIT IV INTERIOR POINT METHODS 9

Karmarkar's algorithm–Projection Scaling method–Dual affine algorithm–Primal affine algorithm Barrier algorithm.

UNIT V DYNAMIC PROGRAMMING 9

Formulation of Multi stage decision problem–Characteristics–Concept of sub-optimization and the principle of optimality–Formulation of Dynamic programming–Backward and Forward recursion– Computational procedure–Conversion offinal value problem in to Initial value problem.

TOTAL: 45 PERIODS

OUTCOMES:

- To understand ethical issues, environmental impact and acquire management skills.

TEXT BOOKS:

1. Hillier and Lieberman "Introduction to Operations Research", TMH, 2000.
2. R.Panneerselvam, "Operations Research", PHI, 2006
3. Hamdy ATaha, "Operations Research –An Introduction", Prentice Hall India, 2003.

REFERENCES:

1. Philips, Ravindran and Solberg, "Operations Research", John Wiley, 2002.
2. Ronald L.Rardin, "Optimization in Operation Research" Pearson Education Pvt. Ltd. New Delhi, 2005.

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S.No.	Subject Code	Subject Name	Contents that included Experimental Learning through Project Work
9	EC6002	Advanced Digital Signal Processing	Power Spectral Density Application of wavelet transform

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EC6002 **ADVANCED DIGITAL SIGNAL PROCESSING** **L T P C**
3 0 0 3

OBJECTIVES:

- To bring out the concepts related to stationary and non-stationary random signals
- To emphasize the importance of true estimation of power spectral density
- To introduce the design of linear and adaptive systems for filtering and linear prediction
- To introduce the concept of wavelet transforms in the context of image processing

UNIT I DISCRETE-TIME RANDOM SIGNALS **9**

Discrete random process – Ensemble averages, Stationary and ergodic processes, Autocorrelation and Autocovariance properties and matrices, White noise, Power Spectral Density, Spectral Factorization, Innovations Representation and Process, Filtering random processes, ARMA, AR and MA processes.

UNIT II SPECTRUM ESTIMATION **9**

Bias and Consistency, Periodogram, Modified periodogram, Blackman-Tukey method, Welch method, Parametric methods of spectral estimation, Levinson-Durbin recursion.

UNIT III LINEAR ESTIMATION AND PREDICTION **9**

Forward and Backward linear prediction, Filtering - FIR Wiener filter- Filtering and linear prediction, non-causal and causal IIR Wiener filters, Discrete Kalman filter.

UNIT IV ADAPTIVE FILTERS **9**

Principles of adaptive filter – FIR adaptive filter – Newton's Steepest descent algorithm – LMS algorithm – Adaptive noise cancellation, Adaptive equalizer, Adaptive echo cancellers.

UNIT V WAVELET TRANSFORM **9**

Multiresolution analysis, Continuous and discrete wavelet transform, Short Time Fourier Transform, Application of wavelet transform, Cepstrum and Homomorphic filtering.

TOTAL: 45 PERIODS

OUTCOMES:

Upon completion of the course, students will be able to:

- Explain the parametric methods for power spectrum estimation.
- Discuss adaptive filtering techniques using LMS algorithm and the applications of adaptive filtering.
- Analyze the wavelet transforms.

TEXT BOOKS:

1. Monson H, Hayes, "Statistical Digital Signal Processing and Modeling", John Wiley and Sons Inc., New York, Indian Reprint, 2007.
2. John G.Proakis, Dimitris G. Manolakis, "Digital Signal Processing", Pearson, Fourth, 2007.
3. Dwight F. Mix, "Random Signal Processing", Prentice Hall, 1995.

REFERENCE:

1. Sophocles J. Orfanidis, "Optimum Signal Processing, An Introduction", McGraw Hill, 1990.

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S.No.	Subject Code	Subject Name	Contents that included Experimental Learning through Project Work
10	EE6801	Electric Energy Generation, Utilization andConservation	Street lighting Feed in Invertors

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EE6801 ELECTRIC ENERGY GENERATION, UTILIZATION AND CONSERVATION

LT P C
3 0 0 3

OBJECTIVES:

- To analyze the various concepts behind renewable energy resources.
- To introduce the energy saving concept by different ways of illumination.
- To understand the different methods of electric heating and electric welding.
- To introduce knowledge on Solar Radiation and Solar Energy Collectors
- To introduce concepts of Wind Energy and its utilization

UNIT I ELECTRIC DRIVES AND TRACTION 9

Fundamentals of electric drive - choice of an electric motor - application of motors for particular services - traction motors - characteristic features of traction motor - systems of railway electrification - electric braking - train movement and energy consumption - traction motor control - track equipment and collection gear.

UNIT II ILLUMINATION 9

Introduction - definition and meaning of terms used in illumination engineering - classification of light sources - incandescent lamps, sodium vapour lamps, mercury vapour lamps, fluorescent lamps – design of illumination systems - indoor lighting schemes - factory lighting halls - outdoor lighting schemes - flood lighting - street lighting - energy saving lamps, LED.

UNIT III HEATING AND WELDING 9

Introduction - advantages of electric heating – modes of heat transfer - methods of electric heating - resistance heating - arc furnaces - induction heating - dielectric heating - electric welding – types - resistance welding - arc welding - power supply for arc welding - radiation welding.

UNIT IV SOLAR RADIATION AND SOLAR ENERGY COLLECTORS 9

Introduction - solar constant - solar radiation at the Earth's surface - solar radiation geometry – estimation of average solar radiation - physical principles of the conversion of solar radiation into heat flat-plate collectors - transmissivity of cover system - energy balance equation and collector efficiency - concentrating collector - advantages and disadvantages of concentrating collectors - performance analysis of a cylindrical - parabolic concentrating collector – Feedin Invertors.

UNIT V WIND ENERGY 9

Introduction - basic principles of wind energy conversion - site selection considerations - basic components of a WECS (Wind Energy Conversion System) - Classification of WECS - types of wind Turbines - analysis of aerodynamic forces acting on the blade - performances of wind.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to understand and analyze power system operation, stability, control and protection.
- Ability to handle the engineering aspects of electrical energy generation and utilization.

TEXT BOOKS:

1. N.V. Suryanarayana, "Utilisation of Electric Power", Wiley Eastern Limited, New Age International Limited, 1993.
2. J.B.Gupta, "Utilisation Electric power and Electric Traction", S.K.Kataria and Sons, 2000.
3. G.D.Rai, "Non-Conventional Energy Sources", Khanna Publications Ltd., New Delhi, 1997.

REFERENCES:

1. R.K.Rajput, Utilisation of Electric Power, Laxmi publications Private Limited.,2007.
2. H.Partab, Art and Science of Utilisation of Electrical Energy", Dhanpat Rai and Co., New Delhi, 2004.
1. C.L.Wadhwa, "Generation, Distribution and Utilisation of Electrical Energy", New Age International Pvt.Ltd., 2003.
2. S. Sivanagaraju, M. Balasubba Reddy, D. Srilatha,' Generation and Utilization of Electrical Energy', Pearson Education, 2010.
3. Donals L. Steeby,' Alternative Energy Sources and Systems', Cengage Learning, 2012

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S.No.	Subject Code	Subject Name	Contents that included Experimental Learning through Project Work
11	EE6502	Microprocessors and Microcontrollers	Look up table A/D and D/A converters

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EE6502 **MICROPROCESSORS AND MICROCONTROLLERS** **L T P C**
3 0 0 3

OBJECTIVES:

- To study the Architecture of uP8085 & uC 8051
- To study the addressing modes & instruction set of 8085 & 8051.
- To introduce the need & use of Interrupt structure 8085 & 8051.
- To develop skill in simple applications development with programming 8085 & 8051
- To introduce commonly used peripheral / interfacing

UNIT I **8085 PROCESSOR** **9**

Hardware Architecture, pinouts – Functional Building Blocks of Processor – Memory organization – I/O ports and data transfer concepts– Timing Diagram – Interrupts.

UNIT II **PROGRAMMING OF 8085 PROCESSOR** **9**

Instruction -format and addressing modes – Assembly language format – Data transfer, data manipulation& control instructions – Programming: Loop structure with counting & Indexing – Look up table - Subroutine instructions - stack.

UNIT III **8051 MICRO CONTROLLER** **9**

Hardware Architecture, pintouts – Functional Building Blocks of Processor – Memory organization – I/O ports and data transfer concepts– Timing Diagram – Interrupts- Comparison to Programming concepts with 8085.

UNIT IV **PERIPHERAL INTERFACING** **9**

Study on need, Architecture, configuration and interfacing, with ICs: 8255 , 8259 , 8254,8237,8251, 8279 ,- A/D and D/A converters &Interfacing with 8085& 8051.

UNIT V **MICRO CONTROLLER PROGRAMMING & APPLICATIONS** **9**

Data Transfer, Manipulation, Control Algorithms& I/O instructions – Simple programming exercises- key board and display interface – Closed loop control of servo motor- stepper motor control – Washing Machine Control.

TOTAL : 45 PERIODS

OUTCOMES:

- Ability to understand and analyse, linear and digital electronic circuits.
- To understand and apply computing platform and software for engineering problems.

TEXT BOOKS:

1. Krishna Kant, "Microprocessor and Microcontrollers", Eastern Company Edition, Prentice Hall of India, New Delhi , 2007.
2. R.S. Gaonkar, 'Microprocessor Architecture Programming and Application', with 8085, Wiley Eastern Ltd., New Delhi, 2013.
3. Soumitra Kumar Mandal, Microprocessor & Microcontroller Architecture, Programming & Interfacing using 8085,8086,8051,McGraw Hill Edu,2013.

REFERENCES:

1. Muhammad Ali Mazidi & Janice Gilli Mazidi, R.D.Kinely 'The 8051 Micro Controller and Embedded Systems', PHI Pearson Education, 5th Indian reprint, 2003.
2. N.Senthil Kumar, M.Saravanan, S.Jeevananthan, "Microprocessors and Microcontrollers', Oxford,2013.
3. Valder – Perez, "Microcontroller – Fundamentals and Applications with Pic," Yeesdee Publishers, Tayler & Francis, 2013.

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S.No.	Subject Code	Subject Name	Contents that included Experimental Learning through Project Work
12	EE6001	Visual Languages and Applications	Ellipse – Polygons and other shapes. GDI pens – Brushes - GDI fonts - Deleting GDI objects The C button class – C list box class – C static class - The font view application – C edit class

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EE6001 VISUAL LANGUAGES AND APPLICATIONS L T P C
3 0 0 3

OBJECTIVES:

- To study about the concepts of windows programming models, MFC applications, drawing with the GDI, getting inputs from Mouse and the Keyboard.
- To study the concepts of Menu basics, menu magic and classic controls of the windows programming using VC++.
- To study the concept of Document/View Architecture with single & multiple document interface, toolbars, status bars and File I/O Serialization.
- To study about the integrated development programming event driven programming, variables, constants, procedures and basic ActiveX controls in visual basic.
- To understand the database and the database management system, visual data manager, data bound controls and ADO controls in VB.

UNIT I FUNDAMENTALS OF WINDOWS AND MFC 9

Messages - Windows programming - SDK style - Hungarian notation and windows data types - SDK programming in perspective. The benefits of C++ and MFC - MFC design philosophy – Document / View architecture - MFC class hierarchy - AFX functions. Application object - Frame window object - Message map. Drawing the lines – Curves – Ellipse – Polygons and other shapes. GDI pens – Brushes - GDI fonts - Deleting GDI objects and deselecting GDI objects. Getting input from the mouse: Client & Non-client - Area mouse messages - Mouse wheel - Cursor. Getting input from the keyboard: Input focus - Keystroke messages - Virtual key codes - Character & dead key messages.

UNIT II RESOURCES AND CONTROLS 9

Creating a menu – Loading and displaying a menu – Responding to menu commands – Command ranges - Updating the items in menu, update ranges – Keyboard accelerators. Creating menus programmatically - Modifying menus programmatically - The system menu - Owner draw menus – Cascading menus - Context menus. The C button class – C list box class – C static class - The font view application – C edit class – C combo box class – C scrollbar class. Model dialog boxes – Modeless dialog boxes.

UNIT III DOCUMENT / VIEW ARCHITECTURE 9

The in existence function revisited – Document object – View object – Frame window object – Dynamic object creation. SDI document template - Command routing. Synchronizing multiple views of a document – Mid squares application – Supporting multiple document types – Alternatives to MDI. Splitter Windows: Dynamic splitter window – Static splitter windows. Creating & initializing a toolbar - Controlling the toolbar's visibility – Creating & initializing a status bar - Creating custom status bar panes – Status bar support in appwizard. Opening, closing and creating the files - Reading & Writing – C file derivatives – Serialization basics - Writing serializable classes.

UNIT IV FUNDAMENTALS OF VISUAL BASIC 9

Menu bar – Tool bar – Project explorer – Toolbox – Properties window – Form designer – Form layout – Intermediate window. Designing the user interface: Aligning the controls – Running the application – Visual development and event driven programming.

Variables: Declaration – Types – Converting variable types – User defined data types - Lifetime of a variable. Constants - Arrays – Types of arrays. Procedures: Subroutines – Functions – Calling procedures. Text box controls – List box & Combo box controls – Scroll bar and slider controls – File controls.

UNIT V DATABASE PROGRAMMING WITH VB 9

Record sets – Data control – Data control properties, methods. Visual data manager: Specifying indices with the visual data manager – Entering data with the visual data manager. Data bound list control – Data bound combo box – Data bound grid control. Mapping databases: Database object – Table def object, Query def object. Programming the active database objects – ADO object model – Establishing a connection - Executing SQL statements – Cursor types and locking mechanism – Manipulating the record set object – Simple record editing and updating.

TOTAL = 45 PERIODS

OUTCOMES:

- To understand and apply computing platform and software for engineering problems.

TEXT BOOKS:

1. Jeff Prosise, 'Programming Windows With MFC', Second Edition, WP Publishers & Distributors (P) Ltd, Reprinted, 2002.
2. Evangelos Petroutsos, 'Mastering Visual Basic 6.0', BPB Publications, 2002.

REFERENCES:

1. Herbert Schildt, 'MFC Programming From the Ground Up', Second Edition, Tata McGraw Hill, reprinted, 2002.
2. John Paul Muller, 'Visual C++ 6 From the Ground Up Second Edition', Tata McGraw Hill, Reprinted, 2002.
3. Curtis Smith & Micheal Amundsen, 'Teach Yourself Database Programming with Visual Basic 6 in 21 days', Techmedia Pub, 1999.

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S.No	Subject Code	Subject Name	Contents that included Experimental Learning through Project Work
13	EI6704	Biomedical Instrumentation	Photo Plethysmography, Body Plethysmography-Blood Gas analyzers ECG – EEG – EMG – ERG Lead systems and recording methods – Typical waveforms

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EI6704 BIOMEDICAL INSTRUMENTATION L T P C
3 0 0 3

OBJECTIVES:

- To Introduce Fundamentals of Biomedical Engineering
- To study the communication mechanics in a biomedical system with few examples
- To study measurement of certain important electrical and non-electrical parameters
- To understand the basic principles in imaging techniques
- To have a basic knowledge in life assisting and therapeutic devices

UNIT I FUNDAMENTALS OF BIOMEDICAL ENGINEERING 9

Cell and its structure – Resting and Action Potential – Nervous system and its fundamentals - Basic components of a biomedical system- Cardiovascular systems- Respiratory systems -Kidney and blood flow - Biomechanics of bone - Biomechanics of soft tissues - Basic mechanics of spinal column and limbs -Physiological signals and transducers - Transducers – selection criteria – Piezo electric, ultrasonic transducers - Temperature measurements - Fibre optic temperature sensors.

UNIT II NON ELECTRICAL PARAMETERS MEASUREMENT AND DIAGNOSTIC PROCEDURES 9

Measurement of blood pressure - Cardiac output - Heart rate - Heart sound - Pulmonary function measurements – spirometer – Photo Plethysmography, Body Plethysmography – Blood Gas analysers, pH of blood –measurement of blood pCO2, pO2, finger-tip oxymeter - ESR, GSR measurements.

UNIT III ELECTRICAL PARAMETERS ACQUISITION AND ANALYSIS 9

Electrodes – Limb electrodes –floating electrodes – pregelled disposable electrodes - Micro, needle and surface electrodes – Amplifiers, Preamplifiers, differential amplifiers, chopper amplifiers – Isolation amplifier - ECG – EEG – EMG – ERG – Lead systems and recording methods – Typical waveforms - Electrical safety in medical environment, shock hazards – leakage current-Instruments for checking safety parameters of biomedical equipments.

UNIT IV IMAGING MODALITIES AND ANALYSIS 9

Radio graphic and fluoroscopic techniques – Computer tomography – MRI – Ultrasonography – Endoscopy – Thermography –Different types of biotelemetry systems - Retinal Imaging - Imaging application in Biometric systems - Analysis of digital images.

UNIT V LIFE ASSISTING, THERAPEUTIC AND ROBOTIC DEVICES 9

Pacemakers – Defibrillators – Ventilators – Nerve and muscle stimulators – Diathermy – Heart – Lung machine – Audio meters – Dialysers – Lithotripsy - ICCU patient monitoring system - Nano Robots - Robotic surgery – Advanced 3D surgical techniques- Orthopedic prostheses fixation.

TOTAL: 45 PERIODS

OUTCOMES:

- Ability to understand and analyze Instrumentation systems and their applications to various industries.

TEXT BOOKS:

1. Leslie Cromwell, Biomedical Instrumentation and Measurement, Prentice hall of India, New Delhi, 2007.
2. Joseph J.carr and John M. Brown, Introduction to Biomedical Equipment Technology, John Wiley and sons, New York, 4th Edition, 2012.
3. Khandpur R.S, Handbook of Biomedical Instrumentation, , Tata McGraw-Hill, New Delhi, 2nd Edition, 2003.

REFERENCES:

1. John G. Webster, Medical Instrumentation Application and Design, John Wiley and sons, New York, 1998.
2. Duane Knudson, Fundamentals of Biomechanics, Springer, 2nd Edition, 2007.
3. Suh, Sang, Gurupur, Varadraj P., Tanik, Murat M., Health Care Systems, Technology and Techniques, Springer, 1st Edition, 2011.
4. Ed. Joseph D. Bronzino, The Biomedical Engineering Hand Book, Third Edition, Boca Raton, CRC Press LLC, 2006.
5. M.Arumugam, 'Bio-Medical Instrumentation', Anuradha Agencies, 2003.

UNDERGROUND CABLE FAULT LOCATION USING RASPERRY PI & IoT

A PROJECT REPORT

Submitted by

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U. DEEPIKA (311814105004)

J. FATAHUNISSA (311814105006)

N. ROSALINDA (311814105018)

In partial fulfillment for the award of the degree

of

BACHELOR OF ENGINEERING

In

ELECTRICAL AND ELECTRONICS ENGINEERING

ANNA UNIVERSITY: CHENNAI 600 025

APRIL 2018

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BONAFIDE CERTIFICATE

Certified that this project report for **"UNDERGROUND CABLE FAULT LOCATION USING RASPERRY PI & IoT"** is the bonafide work of **"M. BRINDHA (311814105003), U. DEEPIKA (311814105004), J. FATAHUNISSA (311814105006) and N. ROSALINDA (311814105018)"** who carried out the project work under our supervision. Certified further, that to the best of our knowledge the work reported herein does not from part of any other project report or dissertation on the basis of which a degree or award was conferred on an earlier occasion on this or any other candidate.

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ABSTRACT

This paper proposes fault location model for underground power cable using microcontroller and the Internet of Things which is based on the internet, which means the information will be transferred through the internet access. Medium voltage underground cable exhibit incipient, self-clearing faults prior to failing permanently. These events typically last one half-cycle and extinguish at the first natural zero crossing of the current. The magnitude of the half-cycle event is primarily dependent on the location of the fault on the feeder. This reports a method for instantaneous fault location on a resistance grounded system of underground power cables. The aim of this project is to determine the distance of underground cable fault from base station in kilometers and also find the location of that faulty place. This project uses the simple concept of Current Sensor Theory. When any fault like short circuit occurs, voltage drop will vary depending on the length of fault in cable, since the current varies Current Sensor is used to calculate the varying current. The signal conditioner manipulates the change in voltage and a microcontroller is used to make the necessary calculations so that the fault distance is displayed by IoT devices. These fault details are after sent to any access point through the internet and displayed.

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7.3 CONCLUSION

It can achieve higher fault detection accuracy in underground cable, especially for high impedance incipient faults. It can supervise almost the entire length of the cable. It uses the simple concept of Current Transformer Theory so the fault can be easily detected and repaired. It detects the exact location of short circuit fault in the underground cable from feeder end.

The processing speed is higher so the time delay between the detection of fault and displaying of the result is lower. The data can be accessed from anywhere using cloud storage.

7.4 RECOMMENDATIONS FOR FUTURE SCOPE

- In this project it detect only the location of short circuit fault in underground cable line, detecting the location of open circuit fault by using capacitor in ac circuit which measures the change in impedance and calculate the distance of fault we overcome this
- Number of faults can be rectified using log in certain areas.
- We can proceed with similar neural structure for fault section and fault location estimation

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MULTI PURPOSE AUTOMATED ROBOTIC ARM FOR SOLID WASTE MANAGEMENT WITH MOVEMENT RECORDING ABILITY

A PROJECT REPORT

Submitted by

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In partial fulfilment for the award of the degree

of

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BONAFIDE CERTIFICATE

Certified that this project report **"MULTI PURPOSE AUTOMATED ROBOTIC ARM FOR SOLID WASTE MANAGEMENT WITH MOVEMENT RECORDING ABILITY "** is the bonafide work of **"N.NABEEL (311814105014); T.SYEDMOOSA (311814105023); B.VIGNESH (311814105024); A.MOHAMED HAJASHARIFF (311814105305)"** who carried out the project work under my supervision.

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INTERNAL EXAMINER

20-4-18

EXTERNAL EXAMINER

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ABSTRACT

This project proposes solid waste management by using simplified automated robotic arm that can also be controlled manually. The basic operation of this robotic arm is to pick and place objects from the source location to destination location with movement recording ability supported by microcontroller based mechatronic system.

This project also presents the design and implementation of an industrial robot system used for pick and place applications. These robots are automated, programmable and capable of movement on two or more axes. The program uploaded in the microcontroller, need not be altered nor uploaded again for every different loop action recorded. The manual operation of this robotic arm is also simplified for the user to record a loop action.

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CHAPTER - 7

CONCLUSION AND FUTURE SCOPE

This project presents the design and implementation of an industrial robot system used for solid waste management. These robots are automated, programmable and capable of segregation of solid industrial wastes. The pick and place robot is a microcontroller based mechatronic system that picks the solid waste and places at desired location. A working model with single robotic arm is designed which can capable of carrying load around 2 kgs. This robotic arm can be controlled either manually or automatically with recorded motion. This project can also be extended with four robotic arms and higher rating of servomotors for high load applications.

In future, the design can be expanded in a way to interact with the household objects and observing the result with the help of camera system. The challenge for the feature has been analyzed and evaluated because more effort has gone into developing automated system to improve productivity than has gone into the appropriate matching of people and technology.